

Assignment # 4

1. The rate of a particular chemical reaction  $A + B \rightarrow C$  is proportional to the concentrations of the reactants  $A$  and  $B$ :

$$\frac{dC}{dt} = \alpha [A(0) - C(t)] [B(0) - C(t)]$$

Let  $C(0) = 0$ .

- (a) Find  $C(t)$  for  $A(0) \neq B(0)$ .  
(b) Find  $C(t)$  for  $A(0) = B(0)$ .

2. A boat moving initially with constant velocity experiences a resisting force proportional to  $v^n$

$$m \frac{dv}{dt} = -kv^n,$$

where  $v$  is the velocity. Find  $v(t)$  and the position,  $x(t)$ , with the initial conditions  $v(0) = v_0$  and  $x(0) = 0$ .

3. Bernoulli's equation

$$\frac{dy}{dx} + f(x)y = g(x)y^n$$

is nonlinear for  $n > 1$ . Show that the substitution  $u = y^{1-n}$  reduces this equation to a linear equation.

4. Given that one solution of

$$R'' + \frac{1}{r}R' - \frac{m^2}{r^2}R = 0$$

is  $R = r^m$ , show that a second linearly independent solution is  $R = r^{-m}$ .

5. Find the general solution of the differential equation

$$\frac{d^3u}{dt^3} + 6\frac{d^2u}{dt^2} + 12\frac{du}{dt} + 8u = 12e^{-t}$$

6. Find the general solution of the differential equation

$$y'' - 2y' + y = \frac{e^x}{1+x^2} \quad -\infty < x < \infty$$

7. Consider the differential equation

$$\frac{d^2y}{dt^2} + y(t) = g(t)$$

- (a) For the initial value problem

$$y(0) = 0, \quad y'(0) = 0.$$

Show that

$$y = \phi(t) = \int_0^t g(s) \sin(t-s) ds.$$

This formula shows the relation between the input,  $g(t)$ , and the output  $\phi(t)$ . The output at time  $t$  depends on the input from the initial time,  $t = 0$ , through time  $t$ . This integral is the *convolution* of  $\sin(t)$  and  $g(t)$ .

(b) Now let

$$y(0) = y_0, \quad y'(0) = y'_0$$

and show that

$$y(t) = y_0 \cos t + y'_0 \sin t + \int_0^t g(s) \sin(t-s) ds.$$

8. Solve the system

$$\begin{aligned} \ddot{x} &= -2\dot{x} - 5y + 3 \\ \dot{y} &= \dot{x} + 2y \end{aligned}$$

with the initial conditions  $x(0) = 0$ ,  $\dot{x}(0) = 0$ , and  $y(0) = 1$ . *Hint.* Write these equations as a system of first order equations.

9. Consider the linear system of differential equations

$$\dot{\mathbf{x}}(t) = \mathbf{A}\mathbf{x}(t) = \begin{pmatrix} 5 & -3 & -2 \\ 8 & -5 & -4 \\ -4 & 3 & 3 \end{pmatrix} \mathbf{x}(t).$$

(a) Show that  $\lambda = 1$  is a triple eigenvalue of  $\mathbf{A}$ , and that there are only two linearly independent eigenvectors

$$\boldsymbol{\xi}^{(1)} = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}, \quad \boldsymbol{\xi}^{(2)} = \begin{pmatrix} 0 \\ 2 \\ -3 \end{pmatrix}.$$

Find two linearly independent solutions,  $\mathbf{x}^{(1)}(t)$  and  $\mathbf{x}^{(2)}(t)$ , of  $\dot{\mathbf{x}}(t) = \mathbf{A}\mathbf{x}(t)$ .

(b) To find the third solution, assume that

$$\mathbf{x}^{(3)}(t) = \boldsymbol{\xi} t e^t + \boldsymbol{\eta} e^t$$

and show that  $\boldsymbol{\xi}$  and  $\boldsymbol{\eta}$  must satisfy

$$\begin{aligned} (\mathbf{A} - \mathbf{I})\boldsymbol{\xi} &= \mathbf{0} \\ (\mathbf{A} - \mathbf{I})\boldsymbol{\eta} &= \boldsymbol{\xi}. \end{aligned}$$

(c) Show that  $\boldsymbol{\xi} = c_1 \boldsymbol{\xi}^{(1)} + c_2 \boldsymbol{\xi}^{(2)}$ , where  $c_1$  and  $c_2$  are arbitrary constants, is the most general solution of  $(\mathbf{A} - \mathbf{I})\boldsymbol{\xi} = \mathbf{0}$ . Show that in order to solve for  $\boldsymbol{\eta}$  it is necessary that  $c_1 = c_2$ .

(d) Obtain  $\mathbf{x}^{(3)}(t)$ .